

ACAMP Inertial Test & Characterization

Working with ACAMP

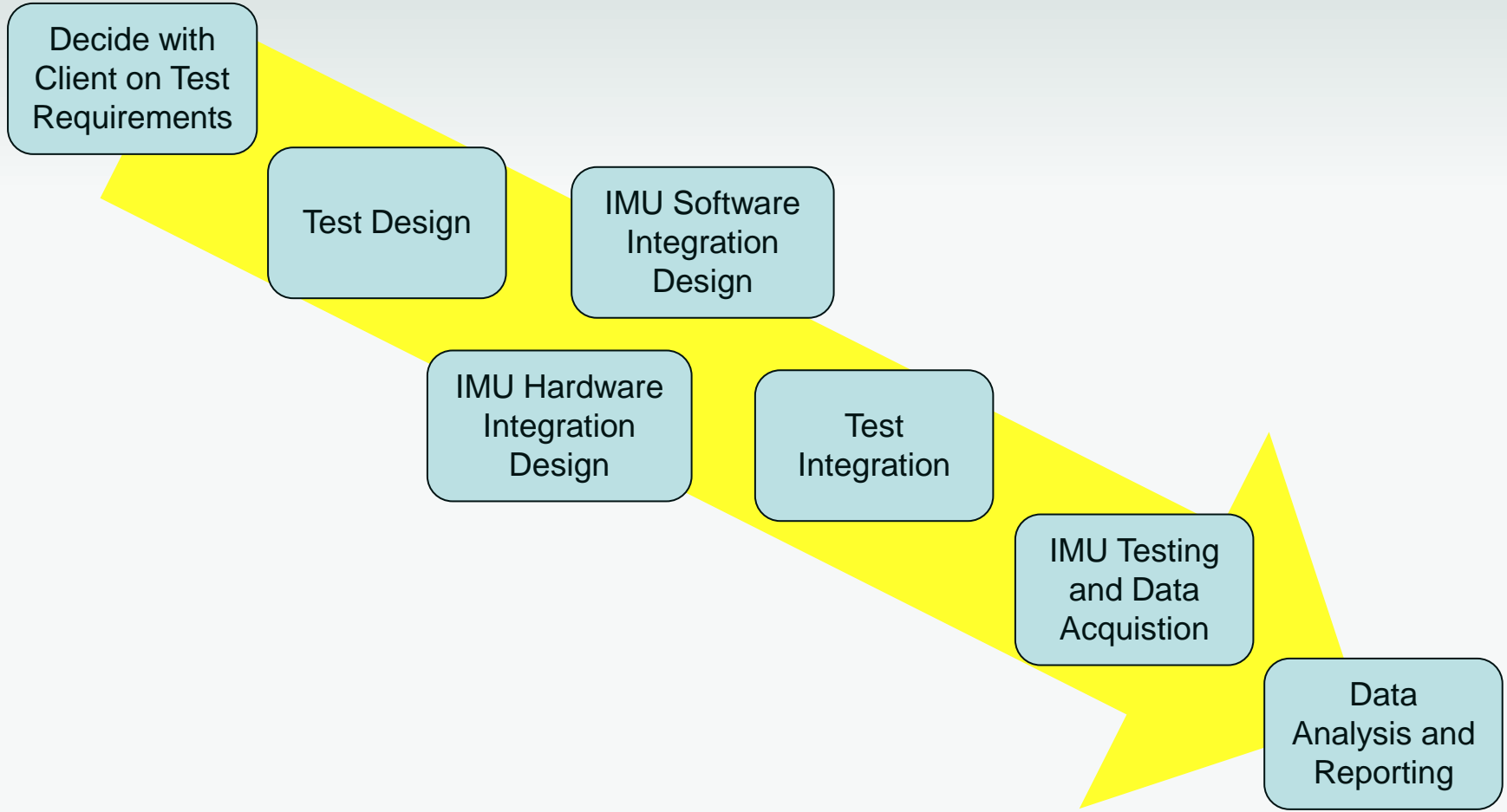


ACAMP INERTIAL DEVELOPMENT

Presentation Agenda

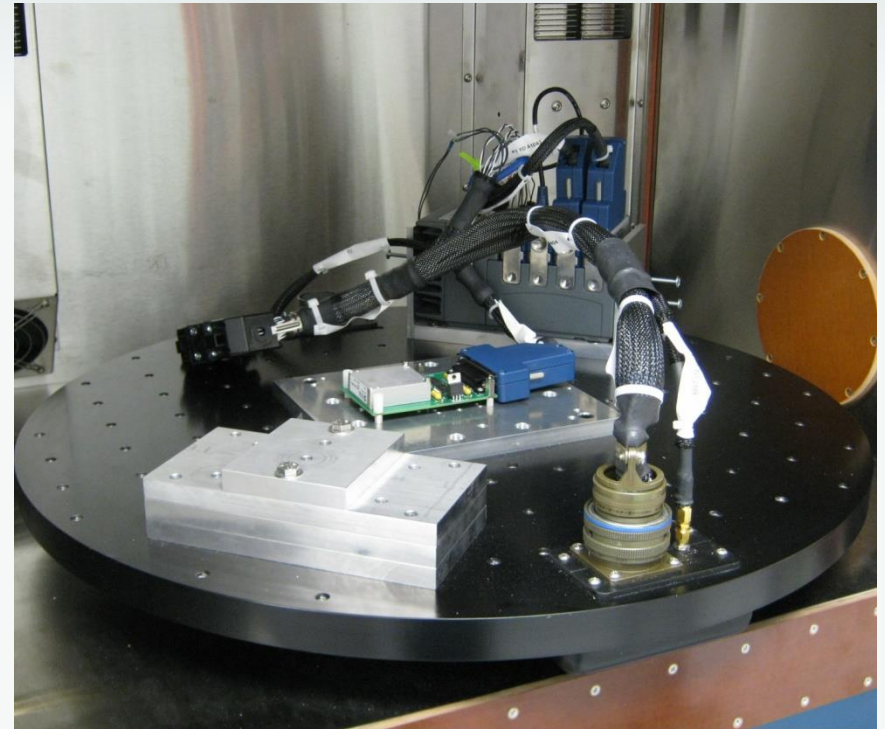
- ❖ Inertial Client Interaction, and Test System Overview
- ❖ Rate Table Testing: Specific Inertial Testing Available



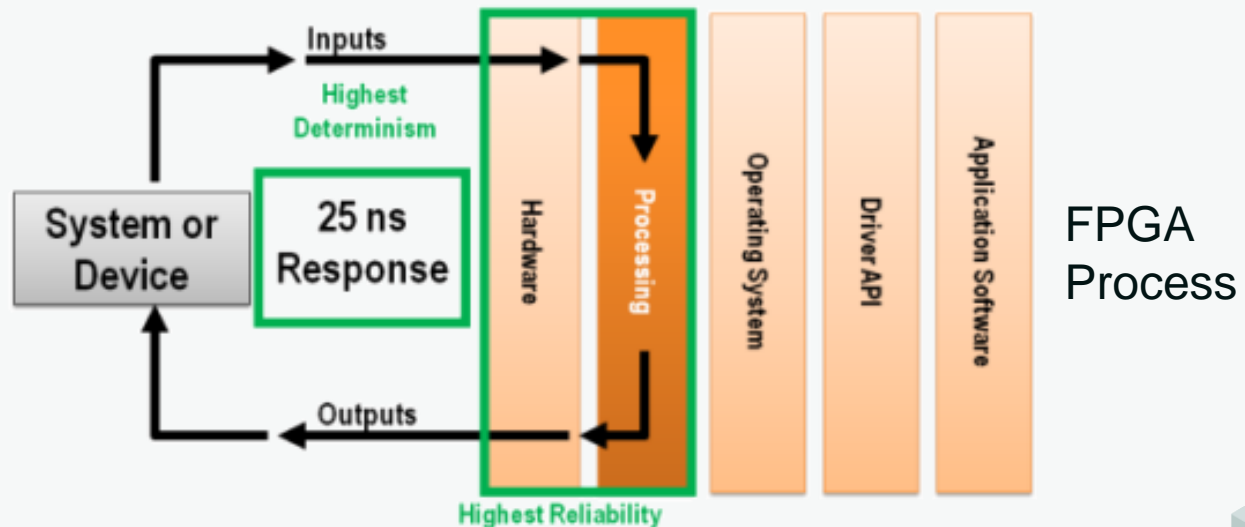
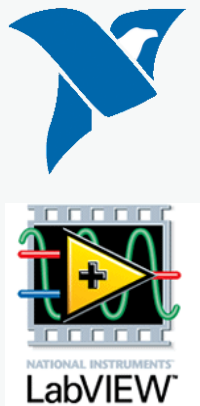


- ❖ Discuss with client what tests are to be done
- ❖ Work out a test process to provide optimal solution
- ❖ ACAMP provides detailed test plan for client approval and provides costing information
 - ❖ Testing plans are taken as much as possible from applicable standards documents

- ❖ Cable design – interface IMU with rate table and DAQ setup
- ❖ Mounting board – IMU strapdown
- ❖ Rate table leveled with respect to IMU

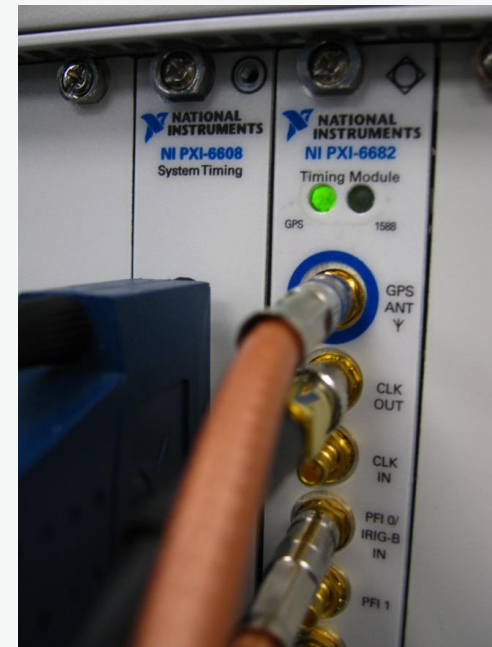
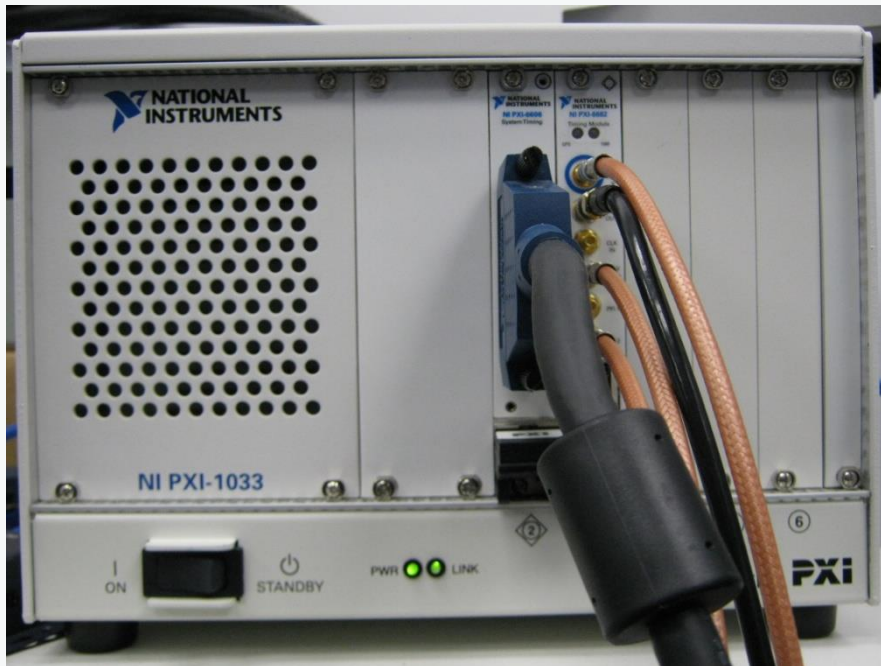


- IMUs communicate with a variety of methods: SPI, RS232, RS485, etc.
- Wholly configurable to each unique IMU interface



System Clock Setup

- Time Setup: Data acquisition triggered by PXI timing module - time stamps and IMU data collection are synced (GPS time)



- IMU data logged to DAQ computer by cRIO real time computer



- Rate table position data logged simultaneously

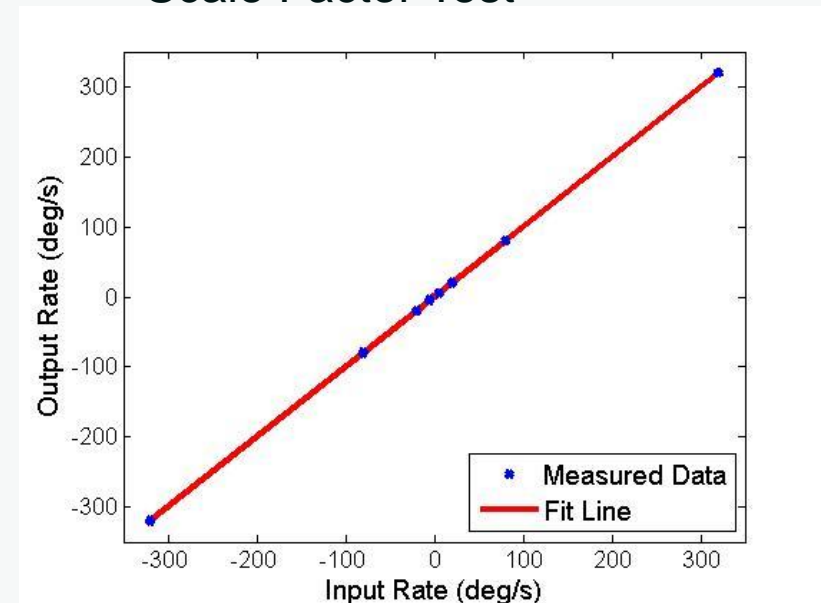
- ❖ NI TestStand integrates and synchronizes entire testing process
- ❖ Test parameters are easily configurable
- ❖ Tests can be modified quickly and easily if needed

Steps: MainSequence	
Step	Description
<ul style="list-style-type: none"> [-] Setup (7) <ul style="list-style-type: none"> Initialize Sequence Control Variables Get Sequence Name Set DAQ command to Connect Initialize Instruments IdentifyUUT Turn Torquers on Run cRIO Host Interface <End Group> [-] Main (7) <ul style="list-style-type: none"> For <ul style="list-style-type: none"> Update Thermal Controller Variables Save Test Step Start Thermal Ramp and Soak Status Monitor Test Profile End 	<ul style="list-style-type: none"> FileGlobals.SkipSoak = FileGlobals.CancelledByUser = File... Locals.Tokens = Split(RunState.SequenceFile.Path, "\\")... FileGlobals.DAQ_Command = 0 Call Initialize Instruments in <Current File> Action, DisplayUUTInformationDialog (modelsupport2.dll) Action, ACAMP - Host PC.Ivproj, Aero4000 - Enable Torq... Call 'My Computer\EPSON - Host Main.vi' Asynchronously... Locals.Index=StationGlobals.RunState.TestStep; Locals.I... Locals.ThermalChamberParameters.Temp_Set_Point = Fil... StationGlobals.RunState.TestStep = Locals.Index, RunSt... Call 'My Computer\Thermal Chamber - Main.vi' Asynchron... Action, ACAMP - Host PC.Ivproj, Status Monitor.vi Call Test Profile in <Current File>

ACAMP can process raw data to provide client with relevant 'datasheet' parameters

- Scale Factor and scale factor errors
- Bias and bias repeatability
- Allan Variance with ARW/VRW and bias stability

Scale Factor Test

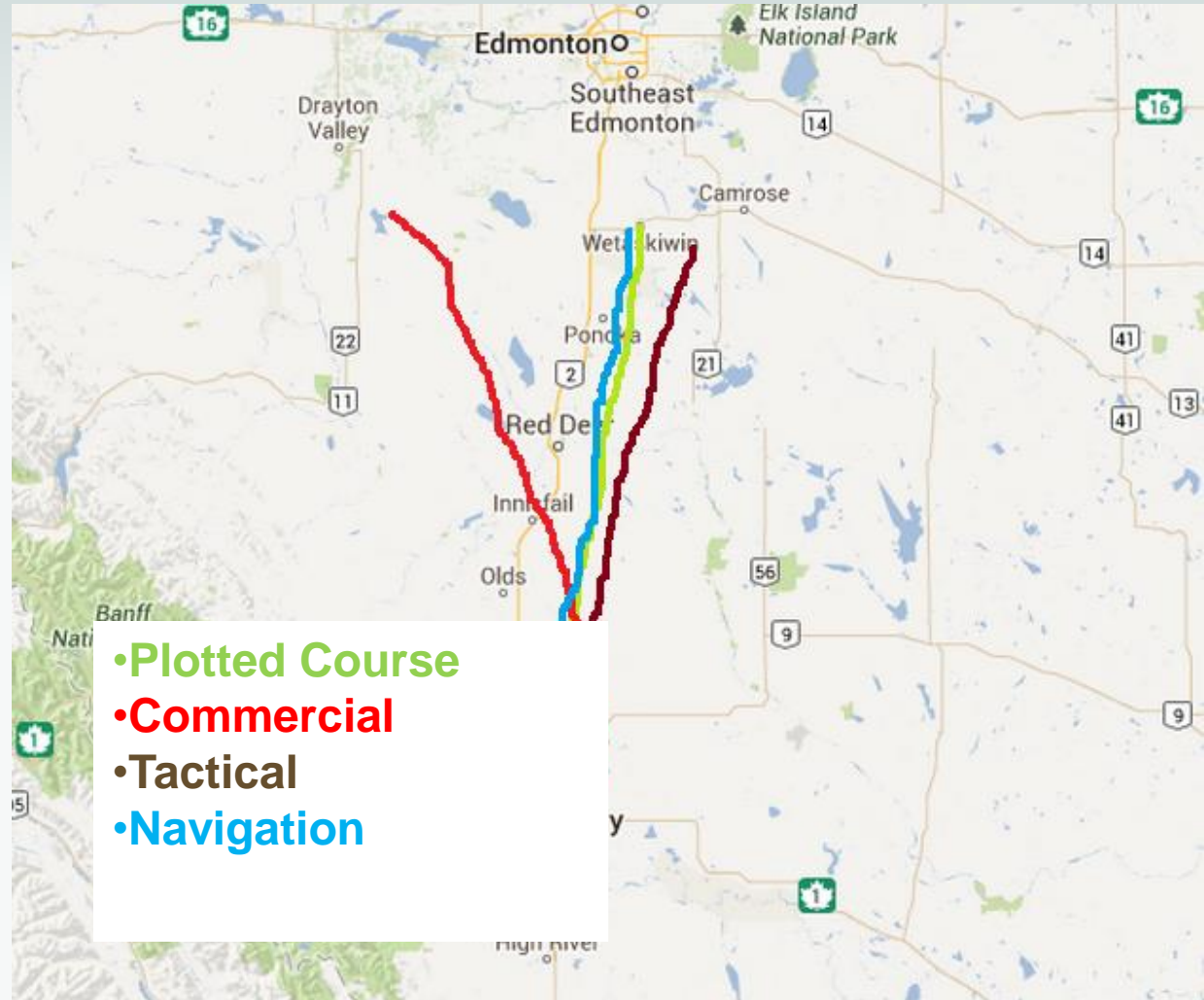


ACAMP INERTIAL DEVELOPMENT

Rate Table Testing: Specific Inertial Testing Available



- Goal is to get where you are trying to go
- Why can't you get there?
 - Various Errors:
 - Noise errors
 - Scale Factor Errors
 - Bias errors



Gyroscope Parameters

- Scale Factor
- Scale Factor Errors
 - Error (1σ)
 - Non-linearity
 - Asymmetry
- Scale Factor Repeatability
- Axis Misalignment
- g -Sensitivity
- Absolute Bias
- Bias Repeatability
- In-Run Bias Instability
- Angular Random Walk
- Temperature Dependence
- Latency Testing

Accelerometer Parameters

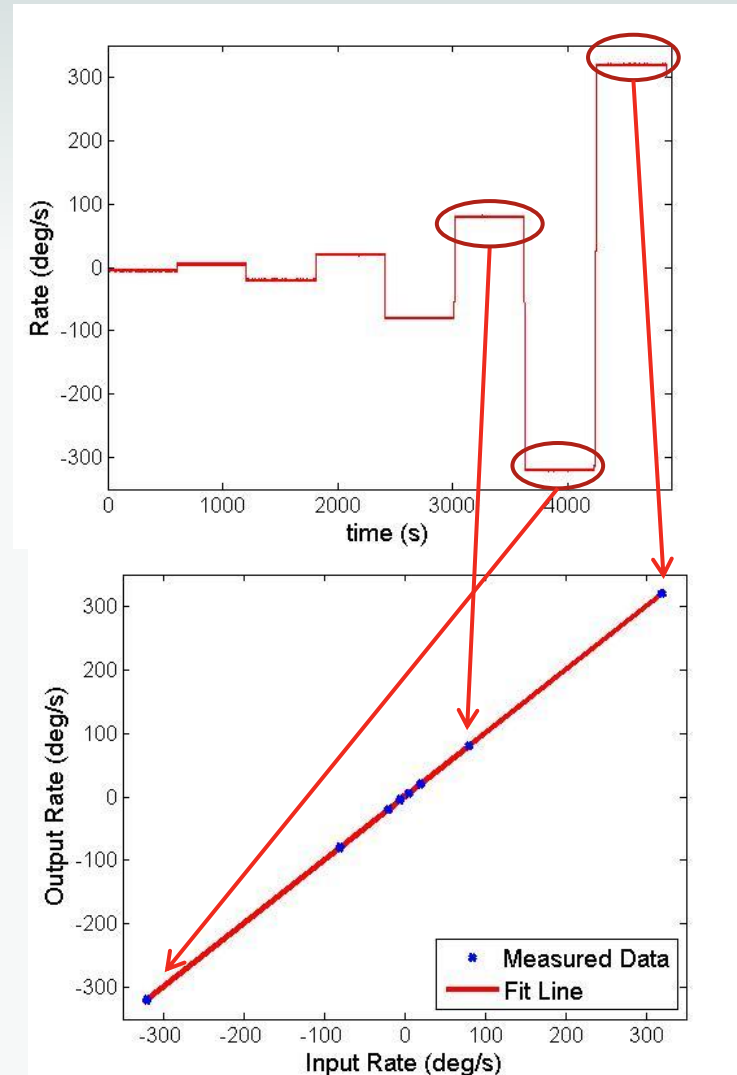
- Scale Factor
- Scale Factor Error (1σ)
- Scale Factor Repeatability
- Axis Misalignment
- Absolute Bias
- Bias Repeatability
- In-Run Bias Instability
- Velocity Random Walk
- Temperature Dependence
- Latency Testing

IMU Specs Available

- ◆ Gyroscope Specs
 - ◆ Scale Factor
 - ◆ Scale Factor Errors
 - ◆ Scale Factor Repeatability
 - ◆ Axis Misalignment

Test Procedure

- ◆ Spin rate table at varying rates, in several orientations



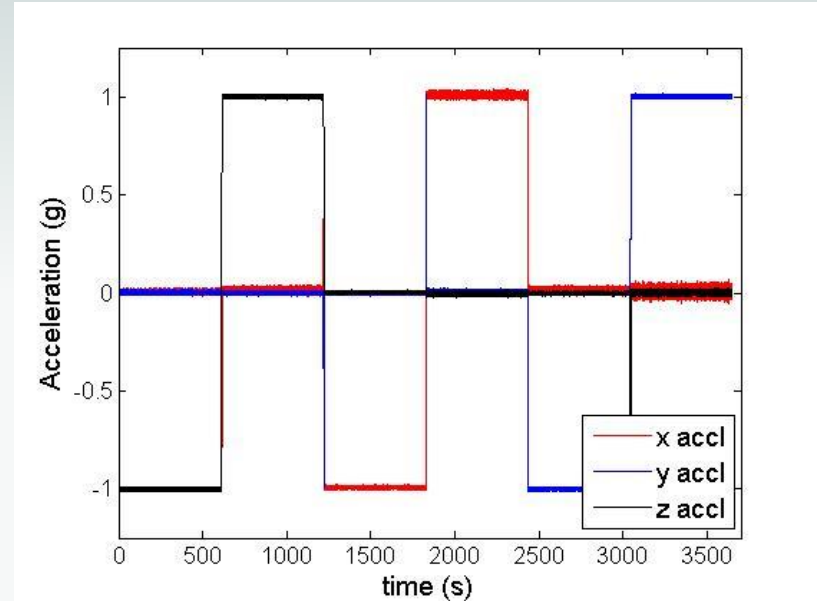
IMU Specs Available

❖ Gyroscope Specs

- ❖ g -Sensitivity
- ❖ Absolute Bias
- ❖ Bias Repeatability

❖ Accelerometer Specs

- ❖ Scale Factor
- ❖ Scale Factor Error (1σ)
- ❖ Scale Factor Repeatability
- ❖ Axis Misalignment
- ❖ Absolute Bias
- ❖ Bias Repeatability



Test Procedure

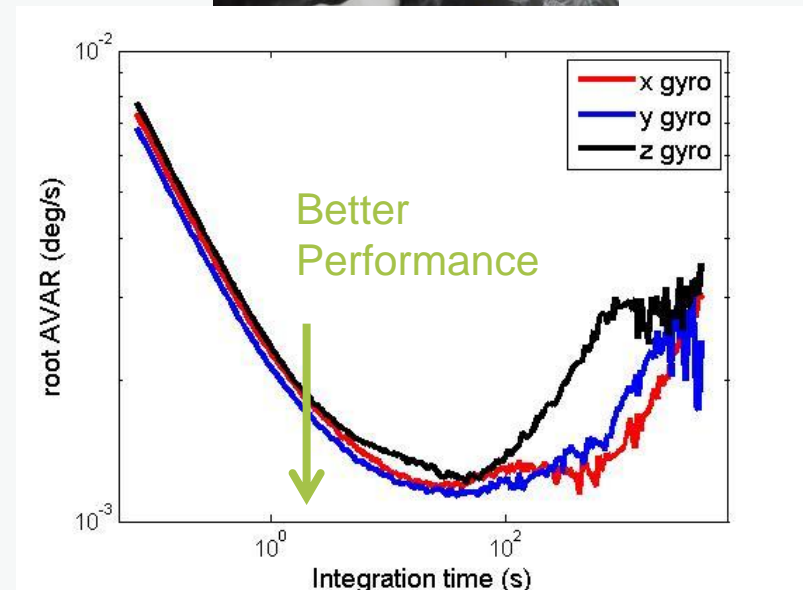
- ❖ Collect static data in 6 orthogonal positions with net-0 external bias

IMU Specs Available

- ❖ Gyroscope Specs
 - ❖ In-Run Bias Instability
 - ❖ Angular Random Walk (ARW)
- ❖ Accelerometer Specs
 - ❖ In-Run Bias Instability
 - ❖ Velocity Random Walk (VRW)

Test Procedure

- ❖ Leave device on stable surface and collect data for long durations of time



Characteristic	ACAMP Measurement	Manufacturer Data Sheet
Absolute Bias (Gyro)	0.2 °/s	1 °/s (1 σ)
Absolute Bias (Accel)	9.1 mg	16 mg (1 σ)
In-Run Bias Stability (Gyro)	11.4 °/hr (1 σ)	12 °/hr (1 σ)
In-Run Bias Stability (Accel)	0.13 mg (1 σ)	0.13 mg (1 σ)
Angular Random Walk	1.74 °/ $\sqrt{\text{hr}}$	1.0 °/ $\sqrt{\text{hr}}$
Velocity Random Walk	0.090 m/s/ $\sqrt{\text{hr}}$	0.076 m/s/ $\sqrt{\text{hr}}$
Scale Factor (Gyro)	0.013105 °/s/LSB	0.01311 °/s/LSB
Scale Factor Error (Gyro)	330 ppm	< 250 ppm
Scale Factor (Accel)	0.81992 mg/LSB	0.8192 mg/LSB
Scale Factor Error (Accel)	320 ppm	< 1000 ppm
g-Sensitivity (Gyro)	0.002 °/s/g	0.013 °/s/g